Implementation Security In Cryptography

Lecture 11: SCA Countermeasures

Recap

- Till the last lecture
 - Side-Channel attacks, evaluation, metrics

Today

• Masking Against SCA

Countermeasure So Far

- We have briefly seen shuffling
- We have briefly experienced random delay
- Both have limited protection
 - Shuffling increases the number of traces linearly
 - Random delay can be undone with a some preprocessing (or DL).

Today's Countermeasure

- Masking
 - Provable security against SCA
 - Exponential security amplification (with some noise)
 - Very well-established

Back to the Leakage Models

Simple Power Model. Let t denote the time, and $\mathcal{N}(t)$ be a normal distributed random variable which represents the noise components. Let f(g,t) denote the power consumption of gate g at the time t. Then a simplified power model for the power consumption is the function

$$P(t) = \sum_{g} f(g, t) + \mathcal{N}(t)$$

- A leakage model leaks a function of the bits processed by a gate
 - So far, we tried to "learn" the leakage model as a function of several bits
 - Now, we go for a simpler yet detailed abstraction

Abstraction of Leakage: Noisy Leakage Model

- Leakage happens from every wire
- The leakage is a noisy function of the value processed in every wire
- SCA attack is basically the probability of the adversary distinguishing between two distribution of power traces:
 - Let the adversary be \mathscr{A} , and its interaction with a distribution D is \mathscr{A}^D . The distribution is basically the from traces **noisy values of the wires**.
 - We are interested in *distinguishing probability* of \mathscr{A}



Chari S, Jutla CS, Rao JR, Rohatgi P (1999) Towards sound approaches to counteract power-analysis attacks. In: CRYPTO. Lecture notes in computer science, vol 1666. Springer, pp 398–412

Abstraction of Leakage: In Simple Words

- Let the adversary be \mathscr{A} , and its interaction with a distribution D is \mathscr{A}^{D} .
 - \bullet We are interested in *distinguishing probability* of ${\mathscr A}$
 - Let the adversary gets power traces corresponding to two different distributions D_0 and D_1 , corresponding to two different secret bits 0, 1.
 - The distinguishing probability is:

$$Pr[A^{D_0} \to 1 - Pr[A^{D_1} \to 1]]$$



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Abstraction of Leakage: Probing model

- Also called threshold probing model
 - Say you have a circuit with *n* wires
 - The adversary can probe t wires of its choice where t < n.
 - The adversary gets exact values of these wires
 - Now:
 - We shall be using probing model to argue our security.
 - But these two models are related !!! I will say a few words on them at the end...

Ishai Y, Sahai A, Wagner DA (2003) Private circuits: securing hardware against probing attacks. In: CRYPTO. Lecture notes in computer science, vol 2729. Springer, pp 463–481



What is Masking?

- Basically a way to make the power consumption uncorrelated with the internal computation
 - Randomize the computation/data
 - Even if you keep the secret same, every time the circuit operates on bits, all of which are random.
 - But maintain correctness
 - You have to ensure that none of the wires carry a bit which is correlated to the actual internal computation.
- So, it is totally an algorithmic trick/strategy.

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What is Masking?

Masking:

- SCA countermeasure.
- Makes power consumption independent of processed data
- Requires fresh randomness at every execution.
- Split a value X into multiple shares $\langle X^1, X^2, \cdots, X^n\rangle$ such that $X^1+X^2+\cdots+X^n=X$.
- Function f(X) is split into functions $\langle f_1, f_2, \dots, f_n \rangle$ such that $f_1(X^1) + f_2(X^2) + \dots + f_n(X^n) = f(X)$.
- Splitting is trivial for linear functions.
- Nonlinear functions require special attention.





• but this definition will be made more relaxed

The First Example

$$a_{m} = a \oplus m_{a}$$

$$b_{m} = b \oplus m_{b}$$

$$q_{m} = q \oplus m_{q}$$

$$q = f(a,b)$$

$$q_{m} = \hat{f}(a_{m}, m_{a}, b_{m}, m_{b}, m_{q})$$

$$q_{m} = (a \cdot b) \oplus m_{q}$$

= $(a_{m} \oplus m_{a}) \cdot (b_{m} \oplus m_{b}) \oplus m_{q}$
= $(((a_{m} \cdot b_{m} \oplus b_{m} \cdot m_{a}) \oplus (m_{b} \cdot a_{m})) \oplus m_{a} \cdot m_{b}) \oplus m_{q}$

The First Example

- There are 4⁵=1024 possible input transmissions that can occur.
- It turns out that the expected value of the energy required for the processing of q=0 and q=1 are identical.
- Thus protected against DPA, under the assumption that the CMOS gates switch only once in one clock cycles.
- But we know there are glitches, and so the output of gates swing a number of times before reaching a steady state. Hence... the argument continues.

Trichina's Gate



- **Observe**!!! The secret dependent values are always blinded with a mask..
- To realize masked AND, just replace the multipliers with AND gates.

First-Order Analysis

- The masking here breaks a value X in two shares X_1 , and X_2 .
- $X = X_1 \oplus X_2$
- Let's consider the leakage as $l = HW(X_1, X_2)$

x	x ₁	<i>x</i> ₂	L(X)	Mean(L(X))	Var(<i>L</i> (<i>X</i>))
0	0	0	0		
0	1	1	2	1	1
1	0	1	1		
1	1	0	1	1	0

- First order analysis does not leak.
 - Note the leakage model
- But second order analysis (and higher order) leaks.
- But we can generalise masking...

Higher-Order Attacks

- Like in a 1st order DPA, where we process on a single point on the power trace, in 2nd order attacks, we exploit the joint leakage of two intermediate values that are processed by the device.
- The attack works in the same way as the 1st order attack, except that we preprocess the trace first.
- For example, if we know the points in the trace when f₁ and f₂ are processed, then combining them would reveal information of unmasked data, and then DPA would still work.
- A common preprocessing operation is to take two power values at different times, say p_{t_1} , p_{t_2} , and determine $(p_{t_1} p_{t_2})^2$

Generalization: compute $(p_{t_1} - \overline{p_{t_1}})(p_{t_2} - \overline{p_{t_2}})$ which works better and is also the second order moment (covariance)

dth-Order Masking

- The masking here breaks a value X in d+1 shares X_1 , and X_2 .
- $X = X_1 \perp X_2 \perp \cdots X_{d+1}$
- \perp is some operator \oplus for operating on gates Boolean masking
 - Can be an integer addition too, Or some more complex encoding
- Each X_i is a share.
- We operate on the shares
- Ideally, (d + 1)th order masking should withstand dth order statistical analysis

Computing on Masks: Linear Function

- $X = X_1 \oplus X_2 \oplus \cdots X_{d+1}$
- $lin(X) = lin(X_1 \oplus X_2 \oplus \dots \oplus X_{d+1}) = lin(X_1) \oplus lin(X_2) \oplus \dots \oplus lin(X_{d+1})$
- Nonlinear (involving ANDs) is tricky

Computing on Masks: Nonlinear Function

- It is challenging for nonlinear functions.
- Example: $f(X, Y) = Z \bigoplus XY$
- Masked Circuit:
 - $f_1(X_1, Y_1) = Z_1 \bigoplus X_1 Y_1$
 - $f_2(X_1, X_2, Y_1, Y_2) = ((Z_2 \oplus X_1Y_2) \oplus X_2Y_1) \oplus X_2Y_2$
- Note again the ordering of the operations is very important!
 - Don't do, $f_2(X_1, X_2, Y_1, Y_2) = (Z_2 \bigoplus X_1Y_2) \bigoplus (X_2Y_1 \bigoplus X_2Y_2)$...as the second parenthesis is dependent on Y
- However, this is not secure against higher order attacks.
- Actually, not even 1st order attacks if there are glitches.

Masking in Leakage Models

• Noisy leakage Model:

- Each wire leaks its noisy value (independently!!).
- But then would masking stand?
- Noise saves your back...
- It has been proven that for distinguishing probability α , masking order d, and noise standard deviation σ , the number of observations needed is lowerbounded by $\sigma^{d+4\log\alpha/\log\sigma}$ — that is exponential security amplification!!!
- But the downside of this model is that you cannot prove security of your masked circuits in real life with this. two complex to handle the noise etc in formal proofs

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Masking in Leakage Models

- Threshold Probing Model:
 - Upto d wires of adversaries choice leaks their entire value.
 - The choice is not adaptive that is adversary cannot change the choice per execution.
 - Let us consider a masked circuit with t+1 shares

 $X = X_1 \oplus X_2 \oplus \cdots X_{d+1}$

• We prove that for a circuit with n wires, if all possible d-subset of wires are considered one-by-one, **none** of these subsets gives you the actual value of the secret *X*

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Trichina's Gate



- Observe!!! The secret dependent values are always blinded with a mask..
- To realize masked AND, just replace the multipliers with AND gates.

$$a_{m} = (a_{m}b_{m} + (b_{m}m_{a} + (m_{b}a_{m} + (m_{a}m_{b} + m_{q})))$$

But Probing Model Does not Capture Reality!!

- In reality, you leak all wires right?
- But then why probing model is used??
 - Turns out that you can prove
 - Threshold probing security implies noisy probing security
 - Reductions between the models can be shown
- Long story short: You can prove your security in the probing model and it will still remain secure in the noisy probing model with sufficient noise.
- So people go on and keep improving the probing model

Security with Glitches: The Glitch Extended Probing Model $y | y_1 | y_2 | x_2 | z_2 \oplus x_1 y_2 | AND | XOR | AND$





Average glitch power for the AND gate does not depend on y.

Average glitch power for the XOR gate depends on y.

• The glitch-extended probing model says that you (adversary) probe a wire, you get the values of all the variables the wire depends on

Plan for Next Class

• We shall see some really secure masking schemes which are used in practice

Threshold Implementation

- State-of-the-art masking scheme...
- Glitch-resistant
- Motivated by the idea of Multi-party computation

Threshold Implementation (TI)

- So far, we have shown how to construct masking and how vulnerable they are to glitches
- But what are the properties that can help in countering glitches?
- TI defines four such properties:
 - Correctness
 - Uniformity
 - Non-completeness
 - Output Uniformity

Threshold Implementation (TI)

- Consider a mapping $\mathbb{F}_2^n \to \mathbb{F}_2^m$ defined by a vectorial Boolean function $(a_1, a_2, \cdots a_m) = f(x_1, x_2, \cdots x_n)$
- We encode $x_i : (x_i^0, x_i^1, \dots x_i^{s_x})$ input shares of the variable x_i
- We now define a vector of functions \mathbb{F} : $(f_1, f_2, \cdots f_{s_o})$
- The output share of variable a_j are denoted as $(a_i^0, a_j^1, \cdots a_i^{s_o})$
- Let' see a pictorial representation...

Threshold Implementation (TI)



Correctness

- Let $X_i : (x_i^0, x_i^1, \dots, x_i^{s_x})$ is an encoding of the variable x_i
- Let A_j : $(a_j^0, a_j^1, \dots a_j^{s_o})$ be an encoding of the variable a_j
- $\mathbb{X} = [X_1, X_2, \cdots X_n]$, and $\mathbb{A} = [A_1, A_2, \cdots A_m]$
- We have $\operatorname{f\!f}(\mathbb{X}) = \mathbb{A}$
- Correctness implies the following:

•
$$\forall a \in \mathbb{F}_2^m, \mathbb{f}(\mathbb{X}) = \mathbb{A} \implies \sum_{s_o} a^{s_o} = a = \sum_{s_o} f^{s_o}(\mathbb{X}), \forall \mathbb{X} : \mathbb{X} \text{ satisfies } \sum_{s_x} x^{s_x} = x \in \mathbb{F}_2^n$$

• Here ${\tt x}$ can be seen as a value assignment of ${\tt X}$

Uniformity

- Let's for simplicity, denote a random variable X taking value form \mathbb{F}_2^n .
- x denote a value assignment to X
- Also, $\mathbb X$ is the random variable corresponding to the sharing of X
- We define $Sh(x) = \{ x \in \mathbb{F}_2^{ns_x} | x^1 \oplus x^2 \cdots x^{s_x} = x \}$
- X is a value assignment to X.

Uniform Masking: A masking X is uniform if and only if there exists a constant p such that $\forall x$ we have: if $x \in Sh(x)$, then Pr[X = x|X = x] = p, else Pr[X = x|X = x] = 0, and $\sum_{x \in Sh(x)} Pr[X = x] = Pr[X = x]$

Implication: The value of x is independent of any $s_x - 1$ shares if you have an uniform s_x sharing

Uniformity

- Define, \mathbb{X}_i as the r.v denoting the i^th share. Then $\mathbb{X}_{\overline{\iota}}$ denotes the vector without the i^th share
- If masking is uniform $\Rightarrow \mathbb{X}_{\overline{i}}$ and x are independent for any *i*.

•
$$\frac{\Pr[\mathbb{X} = \mathbb{X} | X = x]}{\Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}}, X = x]} = \Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}}, \mathbb{X}_{i} = \mathbb{X}_{\overline{\iota}} | X = x]}{\Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}}, X = x]} = \frac{\Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}}, X = x]}{\Pr[\mathbb{X} = \mathbb{X}_{\overline{\iota}}, X = x]} = \frac{\Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}}, X = x]}{\Pr[\mathbb{X} = \mathbb{X}_{\overline{\iota}}, X = x]} = \Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}} | X = x] \Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}} | X = x] \Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}}] = \frac{\Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}}, X = x]}{\Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}} | X = x]} = p.$$

$$\therefore \Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}}] = \sum_{x} \Pr[\mathbb{X}_{\overline{\iota}} = \mathbb{X}_{\overline{\iota}} | X = x] \Pr[\mathbb{X} = x] = p = 2^{n(1 - s_{x})}$$

Non-Completeness

Masked Circuit:

- $f_1(X_1, Y_1) = Z_1 \bigoplus X_1 Y_1$
- $f_2(X_1, X_2, Y_1, Y_2) = ((Z_2 \oplus X_1Y_2) \oplus X_2Y_1) \oplus X_2Y_2$
- Note, f₂ depends on all the 2 shares. Therefore an attacker probing the corresponding wire can observe all the information required.
- A TI on the other hand ensures that if the attacker probes d wires, it can only provide information for at most $s_{in} 1$ shares, which is independent of the sensitive data.

 d-th order Non-completeness: Any combination of up to d component functions f_i of f <u>must be independent of at least one</u> <u>input share</u>.

Non-Completeness: Nonlinear Functions

- Let, $(X, Y) \in F_2^2$, A = f(X, Y) = XY.
- Following is a 1st order TI:
 - $A_1 = f_1(X_2, X_3, Y_2, Y_3) = X_2Y_2 \oplus X_2Y_3 \oplus X_3Y_2$
 - $A_2 = f_2(X_1, X_3, Y_1, Y_3) = X_3Y_3 \oplus X_1Y_3 \oplus X_3Y_1$
 - $A_3 = f_3(X_1, X_2, Y_1, Y_2) = X_1Y_1 \oplus X_1Y_2 \oplus X_2Y_1$

Non-Completeness: Affine Functions

- An affine function f(X) = A can be implemented with $s \ge d + 1$ component functions to thwart d-th order attacks.
- Construction:

 $f_1(X_1) = A_1 = f(X_1),$ For $2 \le i \le s, f_i(X_i) = A_i$, where f_i is f without constant terms. • Eg, $f(X) = 1 \bigoplus X \Rightarrow f_1(X_1) = 1 \bigoplus X_1, f_i(X_i) = X_i, 2 \le i \le s$

Non-Completeness: The Key Point

If the input mask X of the shared function f is a uniform masking and f is a d-th order TI then the d-th order analysis on the power consumptions of a circuit implementing f does not reveal the unmasked input value x even if the inputs are delayed or glitches occur in the circuit.

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Non-Completeness and Number of Shares

 $\begin{aligned} S(x,y,z) &= x \oplus yz \\ &= (x_1 \oplus x_2 \oplus x_3) \oplus (y_1 \oplus y_2 \oplus y_3) (z_1 \oplus z_2 \oplus z_3) \\ S_1(x_2,x_3,y_2,y_3,z_2,z_3) &= x_2 \oplus y_2 z_2 \oplus y_2 z_3 \oplus y_3 z_2 \\ S_2(x_1,x_3,y_1,y_3,z_1,z_3) &= x_3 \oplus y_3 z_3 \oplus y_3 z_1 \oplus y_1 z_3 \\ S_3(x_1,x_2,y_1,y_2,z_1,z_2) &= x_1 \oplus y_1 z_1 \oplus y_1 z_2 \oplus y_2 z_1 \end{aligned}$

- Here we have first order non-completeness
- **Dependency on the function**: For a function with degree t, you need at least t+1 shares to ensure non-completeness
- So if you want to ensure, **dth order non-completeness**, you need at least **td+1** shares.

- Let, $(X, Y) \in F_2^2$, A = f(X, Y) = XY.
- Following is a 1st order TI:
 - $A_1 = f_1(X_2, X_3, Y_2, Y_3) = X_2Y_2 \oplus X_2Y_3 \oplus X_3Y_2$
 - $A_2 = f_2(X_1, X_3, Y_1, Y_3) = X_3Y_3 \oplus X_1Y_3 \oplus X_3Y_1$
 - $A_3 = f_3(X_1, X_2, Y_1, Y_2) = X_1Y_1 \oplus X_1Y_2 \oplus X_2Y_1$

$$\begin{aligned} X &= 0 \Rightarrow X = X_1 \bigoplus X_2 \bigoplus X_3 = 0 \\ Y &= 0 \Rightarrow Y = Y_1 \bigoplus Y_2 \bigoplus Y_3 = 0 \end{aligned}$$

Distribution of (A_1, A_2, A_3)						
	000	011	101	110		
000	(0,0,0)	(0,0,0)	(0,0,0)	(0,0,0)		
011	(0,0,0)	(1,1,0)	(1,0,1)	(0,1,1)		
101	(0,0,0)	(1,0,1)	(0,1,1)	(1,1,0)		
110	(0,0,0)	(0,1,1)	(1,1,0)	(1,0,1)		

				a_1, a	a_2, a_3			
(x,y)	000	011	101	110	001	010	100	111
(0, 0)	7	3	3	3	0	0	0	0
(0, 1)	7	3	3	3	0	0	0	0
(1, 0)	7	3	3	3	0	0	0	0
(1, 1)	0	0	0	0	5	5	5	1

- This circuit is first order TI, hence secure against first-order attacks
- But what about the case when it is used as input to another circuit.
- Output uniformity becomes crucial...

The average Hamming weights does not depend on (x,y). For example, if (x,y)=(0,1), average HW=(3x2)x3/16=18/16. If (x,y)=(1,1), average HW=((5x1)x3+3x1)/16=18/16

				a_1, a_2	a_2, a_3			
(x, y)	000	011	101	110	001	010	100	111
(0, 0)	7	3	3	3	0	0	0	0
(0, 1)	7	3	3	3	0	0	0	0
(1, 0)	7	3	3	3	0	0	0	0
(1, 1)	0	0	0	0	5	5	5	1



Let's consider the case with X.Y.Z , where Z is uniformly distributed

000	5+5+5+5+5+1=31
011	5+5+1=11
101	5+5+1=11
110	5+5+1=11

Let's consider the case with X.Y.Z , where Z is uniformly distributed

				b_1, b	$_{2}, b_{3}$			
(x, y, z)	000	011	101	110	001	010	100	111
(0, 0, 0)	(37	9	9	9	0	0	0	0
(0, 0, 1)	37	9	9	9	0	0	0	0
(0, 1, 0)	37	9	9	9	0	0	0	0
(0, 1, 1)	37	9	9	9	0	0	0	0
(1, 0, 0)	37	9	9	9	0	0	0	0
(1, 0, 1)	37	9	9	9	0	0	0	0
(1, 1, 0)	31	11	11	11	0	0	0	0
(1, 1, 1)	0	0	0	0	21	21	21	1



Note, for (x,y,z)=(1,1,0), Average Hamming Weight=11x2x3/64=33/32 ,while for first 6 rows it is 27/32. These deviations of means with inputs lead to a 1st-order DPA attack.

Uniform Sharing of a Function

 Uniform Sharing of a Function: The d-th order sharing f is uniform if and only if:

 $\forall x \in F_2^n, \forall a \in F_2^m, with f(x) = a, \forall a \in Sh(a), and s_{out} \ge d + 1$:

$$|\{x \in Sh(x) | f(x) = 0\}| = \frac{2^{n(s_{in}-1)}}{2^{m(s_{out}-1)}}$$

Uniform Sharing of a Function

- If the masking X is uniform and the circuit f is uniform, then masking A of a = f(x), defined by A= f(X) is uniform.
- We show: $\Pr([\mathbb{A} = \mathfrak{a} | A = a]) =$ $\Sigma_{\mathbb{X} \in Sh(x)} \Pr[\mathbb{A} = \mathbb{f}(\mathbb{X}) | A = f(x)] \Pr(\mathbb{X} = \mathbb{X}, X = x)$ x, f(x) = a
- The inner probability in the summation $term=2^{n(s_{in}-1)-m(s_{out}-1)} \Pr(\mathbb{X} = \mathbb{X}|X = x) \Pr[X = x] = 2^{n(s_{in}-1)-m(s_{out}-1)}2^{-n(s_{in}-1)} = 2^{-m(s_{out}-1)} \Pr[X = x]$
- Thus, we have $\Pr[\mathbb{A} = a | A = a) = p = 2^{-m(s_{out}-1)}$, if $a \in Sh(a)$, and 0 otherwise.

TI of XORs

- XOR is a linear function
- Let c = a ⊕ b
- Let a₁, a₂, a₃ be the shares of a and b₁, b₂, b₃ be the shares of b i.e.
 - $a = a_1 \bigoplus a_2 \bigoplus a_3$
 - $b = b_1 \oplus b_2 \oplus b_3$
- Let c₁, c₂, c₃ be the output shares:
 - $c_1 = a_1 \bigoplus b_1$
 - $c_2 = a_2 \bigoplus b_2$
 - c₃ = a₃ ⊕ b₃
- · This is non-complete, uniform and correct
- In fact all the three properties can be achieved using just 2 shares!
- To summarize, TI design for linear functions are EASY!
- XOR + AND is functionally complete, so let us look into TI design of AND gate

TI of ANDs: 2-share is not Enough

- AND is not a linear function
- Let c = ab
- Lets first see whether we can design a 2-share TI
- Let a₁, a₂ be the shares of a and b₁, b₂ be the shares of b i.e.
 - $a = a_1 \bigoplus a_2$
 - $b = b_1 \oplus b_2$
- The two output shares must contain the following 4 terms:
 - a₁b₁
 - a₁b₂
 - a₂b₁
 - a₂b₂
- In no way can these 4 terms be combined into 2-shares without violating non-completeness.
- So, 2 share TI of AND gate is not possible
- We need to increase the number of shares

TI of ANDs: 2-share is not Enough

- Three shares are good for satisfying non completeness
- But still does not satisfy output uniformity
- We need 4 shares for that !!!

• $A_1 = f_1(X_2, X_3, Y_2, Y_3) = X_2Y_2 \oplus X_2Y_3 \oplus X_3Y_2$ • $A_2 = f_2(X_1, X_3, Y_1, Y_3) = X_3Y_3 \oplus X_1Y_3 \oplus X_3Y_1$ • $A_3 = f_3(X_1, X_2, Y_1, Y_2) = X_1Y_1 \oplus X_1Y_2 \oplus X_2Y_1$ $A = X \cdot Y$ $X = x_1 \oplus x_2 \oplus x_3 \oplus x_4$ $Y = y_1 \oplus y_2 \oplus y_3 \oplus y_4$ $A = a_1 \oplus a_2 \oplus a_3 \oplus a_4$ $a_1 = (x_2 \oplus x_3 \oplus x_4) \cdot (y_2 \oplus y_3) \oplus y_3$ $a_2 = ((x_1 \oplus x_3) \cdot (y_1 \oplus y_4)) \oplus (x_1 \cdot y_3) \oplus x_4$ $a_3 = (x_2 \oplus x_4) \cdot (y_1 \oplus y_4) \oplus x_4 \oplus y_4$ $a_4 = (x_1 \cdot y_2) \oplus y_3$

- So if you want to ensure, dth order non-completeness, you need at least td+1 shares.
- Also, to ensure uniformity, you need more shares
- That is bad!!!
- So what to do?
- Trick 1: Use fresh randomness

A = X.Y
$X = x_1 \oplus x_2 \oplus x_3$
$Y = y_1 \oplus y_2 \oplus y_3$
$A = a_1 \oplus a_2 \oplus a_3$
$a_1 = (x_2.y_2) \oplus (x_2.y_3) \oplus (x_3.y_2) \oplus \mathbf{r_1} \oplus \mathbf{r_2}$
$a_2 = (x_3.y_3) \oplus (x_1.y_3) \oplus (x_3.y_1) \oplus \mathbf{r_2}$
$\mathbf{a}_3 = (x_1.y_1) \oplus (x_1.y_2) \oplus (x_2.y_1) \oplus \mathbf{r_1}$
r ₁ and r ₂ are 2 bits of randomness
A = X.Y
$X = x_1 \oplus x_2 \oplus x_3$
$Y = y_1 \oplus y_2 \oplus y_3$
$A = a_1 \oplus a_2 \oplus a_3$
$a_1 = (x_2.y_2) \oplus (x_2.y_3) \oplus (x_3.y_2) \oplus r$
$a_2 = (x_3.y_3) \oplus (x_1.y_3) \oplus (x_3.y_1) \oplus (x_1.\mathbf{r}) \oplus (y_1.\mathbf{r})$
$a_3 = (x_1.y_1) \oplus (x_1.y_2) \oplus (x_2.y_1) \oplus (x_1.\mathbf{r}) \oplus (y_1.\mathbf{r}) \oplus \mathbf{r}$
r is a unit of randomness

• Trick 2: Caution!!! Need Registers...



- Why? Because we ensure non-completeness for F and G, through Boolean expressions,
- But not for the entire composition so we need registers.

• Trick 2: Reduce your degree

 $\begin{array}{|c|c|c|} \hline f = XZ \widehat{W} \oplus YW \oplus XY \oplus Y \oplus Z \\ \hline b_1(X,Y,W) = X \oplus Y \oplus XW \oplus YW \\ \hline b_2(X,Y,Z) = Z \oplus XY \oplus XZ \\ \hline b_3(X,Z,W) = X \oplus W \oplus XZ \oplus ZW \\ \hline f(X,Y,Z,W) = b_1 \oplus b_2 \oplus b_1b_3 \oplus b_2b_3 = b_1(b_1,b_2,b_3) \\ \hline \end{array}$

 $b_1 = b_{11} \oplus b_{12} \oplus b_{13}$ $b_2 = b_{21} \oplus b_{22} \oplus b_{23}$ $b_3 = b_{31} \oplus b_{32} \oplus b_{33}$ $X = X_1 \oplus X_2 \oplus X_3$ $Y = Y_1 \oplus Y_2 \oplus Y_3$ $Z = Z_1 \oplus Z_2 \oplus Z_3$ $W = W_1 \oplus W_2 \oplus W_3$

$$\begin{split} b_{11} &= X_1 \oplus Y_2 \oplus (Y_1W_1) \oplus (Y_1W_2) \oplus (Y_2W_1) \oplus (X_1W_1) \oplus (X_1W_2) \oplus (X_2W_1) \\ b_{12} &= X_2 \oplus Y_3 \oplus (Y_2W_2) \oplus (Y_2W_3) \oplus (Y_3W_2) \oplus (X_2W_2) \oplus (X_2W_3) \oplus (X_3W_2) \\ b_{13} &= X_3 \oplus Y_1 \oplus (Y_3W_3) \oplus (Y_3W_1) \oplus (Y_1W_3) \oplus (X_3W_3) \oplus (X_3W_1) \oplus (X_1W_3) \\ b_{21} &= Z_1 \oplus (Z_1X_2) \oplus (Z_2X_1) \oplus (Y_1X_2) \oplus (Y_2X_1) \oplus (Z_1X_1) \oplus (Y_1X_1) \\ b_{22} &= Z_2 \oplus (Z_2X_3) \oplus (Z_3X_2) \oplus (Y_2X_3) \oplus (Y_3X_2) \oplus (Z_2X_2) \oplus (Y_2X_2) \\ b_{23} &= Z_3 \oplus (Z_1X_3) \oplus (Z_3X_1) \oplus (Y_1X_3) \oplus (Y_3X_1) \oplus (Y_3X_3) \oplus (Z_3X_3) \\ b_{31} &= X_1 \oplus W_2 \oplus (Z_1W_1) \oplus (Z_1W_2) \oplus (Z_2W_1) \oplus (X_1Z_1) \oplus (X_1Z_2) \oplus (X_2Z_1) \\ b_{32} &= X_2 \oplus W_3 \oplus (Z_2W_2) \oplus (Z_2W_3) \oplus (Z_3W_2) \oplus (X_2Z_2) \oplus (X_2Z_3) \oplus (X_3Z_2) \\ b_{33} &= X_3 \oplus W_1 \oplus (Z_3W_3) \oplus (Z_3W_1) \oplus (Z_1W_3) \oplus (X_3Z_3) \oplus (X_3Z_1) \oplus (X_1Z_3) \\ \end{split}$$

- Trick 3: Trick of the day
- Better use of registers
 - Registers stop glitch propagation, so why not use them as noncompleteness tool!!!
 - Note that now we can only use d+1 shares for dth order security, and the degree of the function does not matter anymore

$$q^{0} = x^{0}y^{0} + (x^{0}y^{1} + z)$$
$$q^{1} = x^{1}y^{1} + (x^{1}y^{0} + z)$$



Link with Probing Model

- Glitches extend probes
- But register and non-completeness stops probe propagation.
- So, you can check, if you probe one wire here, you still get no information about the actual secret...

$$q^{0} = x^{0}y^{0} + (x^{0}y^{1} + z)$$
$$q^{1} = x^{1}y^{1} + (x^{1}y^{0} + z)$$



Conclusion

• What we didn't study

- More formal treatment of masking in the probing model
- Instead of output uniformity, probing model has a different way of dealing with composition of masked gates **composability**
- We can prove composability but requires more detailed formalization

$$q^{0} = x^{0}y^{0} + (x^{0}y^{1} + z)$$
$$q^{1} = x^{1}y^{1} + (x^{1}y^{0} + z)$$

